

Dot Products

Definition: The dot product of vectors \mathbf{x}, \mathbf{y} in \mathbb{R}^n is the scalar in \mathbb{R} defined by

$$\mathbf{x} \cdot \mathbf{y} = x_1 y_1 + x_2 y_2 + \cdots + x_n y_n \quad (1)$$

Example 1: Calculate $\mathbf{x} \cdot \mathbf{y}$ where

$$\mathbf{x} = \begin{bmatrix} 1 \\ 2 \\ -1 \\ -3 \end{bmatrix}, \quad \mathbf{y} = \begin{bmatrix} -1 \\ 0 \\ -2 \\ 1 \end{bmatrix} \quad (2)$$

$$\vec{x} \cdot \vec{y} = x_1 y_1 + x_2 y_2 + x_3 y_3 + x_4 y_4$$

$$= (1)(-1) + (2)(0) + (-1)(-2) + (-3)(1) = -1 + 0 + 2 - 3 = \boxed{-2}$$

Theorem 1 (Poole 1.2ad): For any vectors \mathbf{x}, \mathbf{y} in \mathbb{R}^n we have

1. $\mathbf{x} \cdot \mathbf{y} = \mathbf{y} \cdot \mathbf{x}$
2. $\mathbf{0} \cdot \mathbf{x} = \mathbf{x} \cdot \mathbf{0} = 0$
3. $\mathbf{x} \cdot \mathbf{x} \geq 0$ and $\mathbf{x} \cdot \mathbf{x} = 0$ if and only if $\mathbf{x} = \mathbf{0}$

Example 2: Justify theorem 1 in \mathbb{R}^2 .

$$1) \vec{x} \cdot \vec{y} = x_1 y_1 + x_2 y_2 = y_1 x_1 + y_2 x_2 = \vec{y} \cdot \vec{x}$$

$$2) \vec{0} \cdot \vec{x} = 0(x_1) + 0(x_2) = 0 \quad \vec{x} \cdot \vec{0} = 0 \text{ by part one}$$

$$3) \vec{x} \cdot \vec{x} = x_1^2 + x_2^2 \geq 0$$

a) Suppose $\vec{x} = \vec{0}$ Then $\vec{x} \cdot \vec{x} = 0$ by part 2

b) Suppose $\vec{x} \cdot \vec{x} = 0$, then $x_1^2 + x_2^2 = 0$

Then $x_1 = x_2 = 0$ and $\vec{x} = \vec{0}$.

Theorem 2 (Poole 1.2bc): For any vectors $\mathbf{x}, \mathbf{y}, \mathbf{z}$ in \mathbb{R}^n and scalar c in \mathbb{R} we have that

1. $\mathbf{x} \cdot (\mathbf{y} + \mathbf{z}) = \mathbf{x} \cdot \mathbf{y} + \mathbf{x} \cdot \mathbf{z}$
2. $\mathbf{x} \cdot (c\mathbf{y}) = c(\mathbf{x} \cdot \mathbf{y})$

Example 3: Justify theorem 2 in \mathbb{R}^2 .

$$\begin{aligned}
 1) \mathbf{x} \cdot (\vec{\mathbf{y}} + \vec{\mathbf{z}}) &= \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \cdot \begin{bmatrix} y_1 + z_1 \\ y_2 + z_2 \end{bmatrix} = x_1(y_1 + z_1) + x_2(y_2 + z_2) \\
 &= \underline{x_1 y_1} + \underline{x_1 z_1} + \underline{x_2 y_2} + \underline{x_2 z_2} = (x_1 y_1 + x_2 y_2) + (x_1 z_1 + x_2 z_2) \\
 &= \vec{\mathbf{x}} \cdot \vec{\mathbf{y}} + \vec{\mathbf{x}} \cdot \vec{\mathbf{z}}
 \end{aligned}$$

$$\begin{aligned}
 2) \vec{\mathbf{x}} \cdot (c\vec{\mathbf{y}}) &= \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \cdot \begin{bmatrix} cy_1 \\ cy_2 \end{bmatrix} = x_1(cy_1) + x_2(cy_2) \\
 &= c(x_1 y_1 + x_2 y_2) \\
 &= c(\vec{\mathbf{x}} \cdot \vec{\mathbf{y}})
 \end{aligned}$$

Example 4: Use theorems 1 and 2 to show that for any vectors $\mathbf{x}, \mathbf{y}, \mathbf{z}$ in \mathbb{R}^n and scalars c, d in \mathbb{R}

$$(c\mathbf{x} + d\mathbf{y}) \cdot \mathbf{z} = c(\mathbf{x} \cdot \mathbf{z}) + d(\mathbf{y} \cdot \mathbf{z}) \quad (3)$$

$$\begin{aligned}
 (c\vec{\mathbf{x}} + d\vec{\mathbf{y}}) \cdot \vec{\mathbf{z}} &= \vec{\mathbf{z}} \cdot (c\vec{\mathbf{x}} + d\vec{\mathbf{y}}) && \text{(theorem 1)} \\
 &= \vec{\mathbf{z}} \cdot (c\vec{\mathbf{x}}) + \vec{\mathbf{z}} \cdot d\vec{\mathbf{y}} && \text{(theorem 2)} \\
 &= c(\vec{\mathbf{z}} \cdot \vec{\mathbf{x}}) + d(\vec{\mathbf{z}} \cdot \vec{\mathbf{y}}) && \text{(theorem 2)} \\
 &= c(\vec{\mathbf{x}} \cdot \vec{\mathbf{z}}) + d(\vec{\mathbf{y}} \cdot \vec{\mathbf{z}}) && \text{(theorem 1)}
 \end{aligned}$$